## Measure-valued - strong uniqueness for hyperbolic systems

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L C Young.

Generalized curves and the existence of an attained absolute minimum in the Calculus of Variations.

Mémoire présenté par M. S. Saks à la séance du 16 décembre 1937

 Introduction. The classical calculus of variations concerned itself only with ptoblems in which a maximum, or minmm, of the variational integral under consideration, was actually attained. It was therefore found necessary to supplement the classical investigations by an existence theory ensuing the existence of an attained extremum in certain types of problems, in order to render the classical ideas applicable.

The restrictions required to build up such an existence theory were of a very drastic kind, and it is natural to ask whether the catalitonia methods cannot be generalized so as to apply to certain types of problems in which the extrema are not utained. These problems still have a definite meaning, and in specifi cases their solutions constitute well-known inequalities which are of great importance in Multyis.

Actually such a generalization is possible, if we introduce a class of elements called generalized admissible curves which may, for the variational problem considered, be regarded as the *closure* of the originally given class of admissible curves. The procedure is merely an adaptation of the ideas which led to the notion of instanal number.

The definition of these generalized curves is implicitly contained in the idea of the note [7]. We give it three explicitly, and in a general form, applicable when the space is a general vector space of the Banch type. We also link it, in an antural way, to the theory of general linear operations, and we employ it to extend the score of the Calculus of Variations by transforming certain types of variations all problems with matchined externa into corresponding problems with matchined externa.

The present methods, when used in conjunction with those of the paper [9], where the classical conditions for a minimum are extended correspondingly, make it possible to solve, in the framework of the Calculus of Variations, important classes of problems concerning unattained minima

## Notation

 $C_0(\mathbb{R}^d)$  – closure of the space of continuous functions on  $\mathbb{R}^d$  with compact support w.r.t. the  $\|\cdot\|_{\infty}$ -norm.  $(C_0(\mathbb{R}^d))^* \cong \mathcal{M}(\mathbb{R}^d)$  – the space of signed Radon measures with finite mass. The duality pairing is given by

$$\langle \mu, f \rangle = \int\limits_{\mathbb{R}^d} f(\lambda) \, d\mu(\lambda).$$

#### Definition

A map  $\mu : \Omega \to \mathcal{M}(\mathbb{R}^d)$  is called weakly\* measurable if the functions  $x \mapsto \langle \mu(x), f \rangle$  are measurable for all  $f \in C_0(\mathbb{R}^d)$ .

## Young measures

- The main feature of Young measure theory is that it allows us to pass to a limit in the expression f(v<sup>j</sup>) with nonlinear f and only weakly-star convergent v<sup>j</sup>.
- What's the strategy? Instead of considering f(v<sup>j</sup>) we embed the problem in a larger space, but gain linearity, i.e. (f, δ<sub>v<sup>j</sup>(x)</sub>).
- If  $f \in C_0(\mathbb{R})$ ) using the duality

$$(L^1(\Omega; C_0(\mathbb{R}^d)))^* \cong L^\infty_w(\Omega; \mathcal{M}(\mathbb{R}^d)),$$

Banach-Alaoglu theorem and weak-star continuity of linear operators allows for limit passage to get  $\langle f, \nu_x \rangle$ .

What's the cost?

We end up with a weaker notion of solution: *measure-valued* solution

# Can the Young measures describe a concentration effect?

#### Definition

A bounded sequence  $\{z^j\}$  in  $L^1(\Omega)$  converges in biting sense to a function  $z \in L^1(\Omega)$ , written  $z^j \stackrel{b}{\to} z$  in  $\Omega$ , provided there exists a sequence  $\{E_k\}$  of measurable subsets of  $\Omega$ , satisfying  $\lim_{k\to\infty} |E_k| = 0$ , such that for each k

$$z^j 
ightarrow z$$
 in  $L^1(\Omega \setminus E_k)$ .

#### Remarks

Biting limit can be also express as  $\lim_{n\to\infty} \lim_{j\to\infty} T^n(z^j)$ , where by  $T^n(\cdot)$  we denote standard truncation operator.

#### Lemma

Let  $u^{j}$  be a sequence of measurable functions and  $\nu_{x}$  a Young measure associated to a subsequence  $u_{j_{k}}$ . Then  $f(\cdot, u^{j_{k}}) \xrightarrow{b} \langle \nu_{x}, f \rangle$ for every Carathéodory function  $f(\cdot, \cdot)$  s.t.  $f(\cdot, u^{j_{k}})$  is a bounded sequence in  $L^{1}(\Omega)$ . Here  $\langle \nu_{x}, f \rangle = \int_{\mathbb{R}^{d}} f \, d\nu_{x}$ .

#### Remarks

In view of the above facts the classical Young measures prescribe only the oscillation effect, not the concentration one. The attempt to prescribe also concentration effect by some generalizations of the Young measures was initiated by DiPerna and Majda

#### Lemma

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#### Remarks

In view of the above facts the classical Young measures prescribe only the oscillation effect, not the concentration one. The attempt to prescribe also concentration effect by some generalizations of the Young measures was initiated by DiPerna and Majda This system models the flow of an inviscid, incompressible fluid with constant density in the absence of external forces, where v(t,x) is the velocity of the fluid and the p(t,x) the pressure

$$v_t + \operatorname{div} (v \otimes v) + \nabla p = 0,$$
  
 $\operatorname{div} v = 0.$ 

- $\nu_{x,t} \in \mathcal{P}(\mathbb{R}^d)$  for a.e.  $(x,t) \in \mathbb{R}^d \times \mathbb{R}^+$  (oscillation measure)
- $m \in \mathcal{M}^+(\mathbb{R}^d \times \mathbb{R}^+)$  (concentration measure)
- $\nu_{x,t}^{\infty} \in \mathcal{P}(\mathcal{S}^{d-1})$  for *m*-a.e.  $(x, t) \in \mathbb{R}^d \times \mathbb{R}^+$ (concentration-angle measure)

R. J. DiPerna and A. J. Majda, Oscillations and concentrations in weak solutions of the incompressible fluid equations, Comm. Math. Phys. 1987.

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R. J. DiPerna and A. J. Majda, Oscillations and concentrations in weak solutions of the incompressible fluid equations, Comm. Math. Phys. 1987.

## Measure-valued solutions to incompressible Euler system

We say that  $(\nu, m, \nu^{\infty})$  is a measure-valued solution of IE with initial data  $u_0$  if for every  $\phi \in C^1_{c.div}([0, \mathcal{T}) \times \mathbb{T}^n; \mathbb{R}^n)$  it holds that

$$\int_0^T \int_{\mathbb{T}^n} \partial_t \phi \cdot \overline{u} + \nabla \phi : \overline{u \otimes u} dx dt + \int_{\mathbb{T}^n} \phi(\cdot, 0) \cdot u_0 dx = 0.$$

Where

$$\overline{u} = \langle \lambda, \nu \rangle$$
  
$$\overline{u \otimes u} = \langle \lambda \otimes \lambda, \nu \rangle + \langle \beta \otimes \beta, \nu^{\infty} \rangle m$$

If the solution is generated by some approximation sequences, then the black terms on right-hand side correspond to the biting limit of sequences whereas the blue ones corespond to concentration measure Let us set

$$E_{mvs}(t) := \int_{\mathbb{T}^n} \frac{1}{2} \overline{|u|^2}(t,x) dx$$

for almost every t, where

$$\overline{|u|^2} = \langle |\lambda|^2, \nu \rangle + \langle |\beta|^2, \nu^{\infty} \rangle m$$

and

$$E_0 := \int_{\mathbb{T}^n} \frac{1}{2} |u_0|^2(x) dx.$$

We then say that a measure-valued solution is admissible if

$$E_{mvs}(t) \leq E_0$$

in the sense of distributions.

• Y. Brenier, C. De Lellis, L. Székelyhidi, Jr., Weak-strong uniqueness for measure-valued solutions. Comm. Math. Phys. 2011,

Incompressible Euler -oscillation and concentration measure,

• S. Demoulini, D. M. A. Stuart, A. E. Tzavaras, Weak-strong uniqueness of dissipative measure-valued solutions for polyconvex elastodynamics. Arch. Ration. Mech. Anal. 2012 *In weak formulation only oscillation measure, in entropy inequality there appears non-negative concentration measure* 

- P. G., A. Świerczewska-Gwiazda, E. Wiedemann, Weak-Strong Uniqueness for Measure-Valued Solutions of Some Compressible Fluid Models, Nonlinearity, 2015 Oscillatory and vector-valued concentration measure both in weak formulation and entropy inequality
- E. Feireisl, P. G., A. Świerczewska-Gwiazda, E. Wiedemann, Dissipative measure-valued solutions to the compressible Navier–Stokes system, Calculus of Variations and Partial Differential Equations, 2016

Instead of vector-valued concentration measure the dissipation defect is introduced

• J. Březina, E. Feireisl, Measure-valued solutions to the complete Euler system, arXiv:1702.04870

#### Theorem (Y. Brenier, C. De Lellis, L. Székelyhidi, Jr., 2011)

Let  $U \in C^1([0, T] \times \mathbb{T}^n)$  be a solution of IE. If  $(\nu, m, \nu^{\infty})$  is an admissible measure-valued solution with the same initial data, then

$$\nu_{t,x} = \delta_{U(t,x)}$$
 for a.e.  $t, x$ , and  $m = 0$ .

#### **Remark:**

Some generalization of this result: Emil Wiedemann, *Weak-strong uniqueness in fluid dynamics*, arXiv:1705.04220

Let's define relative energy (entropy):

$$E_{rel}(t) := \int_{\mathbb{T}^n} \frac{1}{2} \overline{|u - U|^2}(t, x) dx$$

where

$$\overline{|u - U|^2} = \langle |\lambda - U|^2, \nu \rangle + \langle |\beta|^2, \nu^{\infty} \rangle m$$

then

$$\frac{d}{dt}E_{rel}(t) \leq \|U\|_{C^1} \cdot E_{rel}(t).$$

We consider now the isentropic Euler equations,

$$\partial_t(\rho u) + \operatorname{div}(\rho u \otimes u) + \nabla p(\rho) = 0,$$
  
$$\partial_t \rho + \operatorname{div}(\rho u) = 0.$$

We will use the notation for the so-called pressure potential defined as

$$P(\rho) = \rho \int_1^\rho \frac{p(r)}{r^2} dr.$$

## Measure-valued solutions to compressible Euler

- We need a slight refinement which allows us to treat sequences whose components have different growth.
- Let  $(u_k, w_k)_k$  be a sequence such that  $(u_k)$  is bounded in  $L^p(\Omega; \mathbb{R}^l)$  and  $(w_k)$  is bounded in  $L^q(\Omega; \mathbb{R}^m)$   $(1 \le p, q < \infty)$ . Define the nonhomogeneous unit sphere

$$\mathbb{S}_{p,q}^{l+m-1} := \{ (\beta_1, \beta_2) \in \mathbb{R}^{l+m} : |\beta_1|^{2p} + |\beta_2|^{2q} = 1 \}.$$

Then, there exists a a subsequence and measures

$$\nu \in L^{\infty}_{w}(\Omega; \mathcal{P}(\mathbb{R}^{l+m})), m \in \mathcal{M}^{+}(\bar{\Omega}), \ \nu^{\infty} \in L^{\infty}_{w}(\Omega, m; \mathcal{P}(\mathbb{S}^{l+m-1}_{p,q}))$$

such that in the sense of measures

$$f(x, u_n(x), w_n(x))dx \stackrel{*}{\rightharpoonup} \int_{\mathbb{R}^{l+m}} f(x, \lambda_1, \lambda_2) d\nu_x(\lambda_1, \lambda_2) dx + \int_{\mathbb{S}_{p,q}^{l+m-1}} f^{\infty}(x, \beta_1, \beta_2) d\nu_x^{\infty}(\beta_1, \beta_2) m.$$

### General hyperbolic conservation law

 Y. Brenier, C. De Lellis, L. Székelyhidi, Jr., Weak-strong uniqueness for measure-valued solutions. Comm. Math. Phys. 2011,

General hyperbolic systems - only oscillation measure, both in weak formulation and entropy inequality

• S. Demoulini, D. M. A. Stuart, A. E. Tzavaras, Weak-strong uniqueness of dissipative measure-valued solutions for polyconvex elastodynamics. Arch. Ration. Mech. Anal. 2012 *In weak formulation only oscillation measure, in entropy inequality there appears non-negative concentration measure* 

## General hyperbolic conservation law

 C. Christoforou, A. Tzavaras, Relative entropy for hyperbolic-parabolic systems and application to the constitutive theory of thermoviscoelasticity, Arch. Ration. Mech. Anal. 2017
 An analogue result for more general form of a system, hyperbolic-parabolic case, also only with a non-negative

concentration measure in entropy inequality

• P. G., O. Kreml, A. Świerczewska-Gwiazda. Dissipative measure valued solutions for general hyperbolic conservation laws, arXiv:1801.01030

Concentration measure both in the weak formulation and the entropy inequality

We consider the hyperbolic system of conservation laws in the form

$$\partial_t A(u) + \partial_\alpha F_\alpha(u) = 0$$
 (1)

with the initial condition  $u(0) = u_0$ . Here  $u : [0, T] \times \mathbb{T}^d \to \mathbb{R}^n$ . There exists an open convex set  $X \subset \mathbb{R}^n$  such that the mappings  $A : \overline{X} \to \mathbb{R}^n$ ,  $F_\alpha : X \to \mathbb{R}^n$  are  $C^2$  maps on X, A is continuous on  $\overline{X}$  and  $\nabla A(u)$  is nonsingular for all  $u \in X$ .

#### Definition

We say that  $(\nu, m_A, m_{F_{\alpha}}, m_{\eta})$ , is a dissipative measure-valued solution of system (1) if  $\nu \in L^{\infty}_{\text{weak}}((0, T) \times \mathbb{T}^d; \mathcal{P}(\overline{X}))$  is a parameterized measure and together with concentration measures  $m_A \in (\mathcal{M}([0, T] \times \mathbb{T}^d))^n$ ,  $m_{F_{\alpha}} \in (\mathcal{M}([0, T] \times \mathbb{T}^d))^{n \times n}$  satisfy

$$\begin{split} &\int_{Q} \langle \nu_{t,x}, A(\lambda) \rangle \cdot \partial_{t} \varphi dx dt + \int_{Q} \partial_{t} \varphi \cdot m_{A}(dx dt) \\ &+ \int_{Q} \langle \nu_{t,x}, F_{\alpha}(\lambda) \rangle \cdot \partial_{\alpha} \varphi dx dt + \int_{Q} \partial_{\alpha} \varphi \cdot m_{F_{\alpha}}(dx dt) \\ &+ \int_{\mathbb{T}^{d}} \langle \nu_{0,x}, A(\lambda) \rangle \cdot \varphi(0) dx + \int_{\mathbb{T}^{d}} \varphi(0) \cdot m_{A}^{0}(dx) = 0 \end{split}$$
for all  $\varphi \in C_{c}^{\infty}(Q)^{n}$ .

#### Definition

Moreover, the total energy balance holds for all  $\zeta \in C_c^{\infty}([0, T))$ 

$$\int_{Q} \langle v_{t,x}, \eta(\lambda) 
angle \zeta'(t) dx dt + \int_{Q} \zeta'(t) m_{\eta}(dx dt) \ + \int_{\mathbb{T}^d} \langle v_{0,x}, \eta(\lambda) 
angle \zeta(0) dx + \int_{\mathbb{T}^d} \zeta(0) m_{\eta}^0(dx) \ge 0$$

with a dissipation measure  $m_{\eta} \in \mathcal{M}^+([0, \mathcal{T}] \times \mathbb{T}^d)$ . In particular we assume that measures  $m_A^0$  and  $m_n^0$  are well defined.

## Hypotheses

(H1) There exists an entropy-entropy flux pair  $(\eta, q_{\alpha}), \eta(u) \ge 0$ and  $\lim_{|u|\to\infty} \eta(u) = \infty$ This yields the existence of a  $C^1$  function  $G : \overline{X} \to \mathbb{R}^n$  such that

$$abla \eta = \mathbf{G} \cdot \nabla \mathbf{A}, \quad \nabla \mathbf{q}_{\alpha} = \mathbf{G} \cdot \nabla F_{\alpha}, \qquad \alpha = 1, ..., \mathbf{d}.$$

(H2) The symmetric matrix

$$abla^2\eta(u) - G(u)\cdot 
abla^2 A(u)$$

is positive definite for all  $u \in X$ .

(H3) The vector A(u) and the fluxes  $F_{\alpha}(u)$  are bounded by the entropy, i.e.

$$|A(u)| \leq C(\eta(u)+1), \quad |F_{\alpha}(u)| \leq C(\eta(u)+1), \qquad lpha=1,...,d.$$

Define for a strong solution U taking values in a compact set  $D \subset X$  the relative entropy

$$\eta(u|U) := \eta(u) - \eta(U) - \nabla \eta(U) \cdot \nabla A(U)^{-1}(A(u) - A(U))$$
$$= \eta(u) - \eta(U) - G(U) \cdot (A(u) - A(U))$$

and the relative flux as

$$F_{\alpha}(u|U) := F_{\alpha}(u) - F_{\alpha}(U) - \nabla F_{\alpha}(U) \nabla A(U)^{-1}(A(u) - A(U))$$
  
for  $\alpha = 1, ..., d$ .

If we assume (H1) – (H3) hold and  $\lim_{|u|\to\infty} \frac{A(u)}{\eta(u)} = 0$  then  $|F_{\alpha}(u|U)| \leq C\eta(u|U).$  An analogue fact under more restrictive assumptions

$$\lim_{|u|\to\infty}\frac{A(u)}{\eta(u)}=\lim_{|u|\to\infty}\frac{F_{\alpha}(u)}{\eta(u)}=0,$$

was proved in Christoforou & Tzavaras 2017. Note however that this condition is satisfied for polyconvex elastodynamics but is not satisfied e.g. for compressible Euler equations.

Let f(y, u) be a nonnegative continuous function on  $Y \times \overline{X}$  and let g(y, u) be a vector-valued function, also continuous on  $Y \times \overline{X}$ such that

$$\lim_{|u|\to\infty} |g(y,u)| \leq C \lim_{|u|\to\infty} f(y,u).$$

Let  $m_f$  and  $m_g$  denote the concentration measures related to  $f(\cdot, u_n)$  and  $g(\cdot, u_n)$  respectively, where  $f(\cdot, u_n)$  is a sequence bounded in  $L^1$ . Then

 $|m_g| \leq Cm_f,$ 

i.e.  $|m_g|(A) \leq Cm_f(A)$  for any Borel set  $A \subset Y$ .

#### Theorem

Let  $(\nu, m_A, m_{F_{\alpha}}, m_{\eta})$ ,  $\alpha = 1, ..., d$ , be a dissipative measure-valued solution to (1) generated by a sequence of approximate solutions. Let  $U \in W^{1,\infty}(Q)$  be a strong solution to (1) with the same initial data  $\eta(u_0) \in L^1(\mathbb{T}^d)$ , thus  $\nu_{0,x} = \delta_{u_0(x)}$ ,  $m_A^0 = m_{F_{\alpha}}^0 = m_{\eta}^0 = 0$ . Then  $\nu_{t,x} = \delta_{U(x)}$ ,  $m_A = m_{F_{\alpha}} = m_{\eta} = 0$  and u = U a.e. in Q.

#### **Compressible Euler system**

$$\partial_t \rho + \operatorname{div}(\rho v) = 0,$$
  
$$\partial_t(\rho v) + \operatorname{div}(\rho v \otimes v) + \nabla p(\rho) = 0.$$

The associated entropy is given by

$$\eta(\rho, \mathbf{v}) = \frac{1}{2}\rho|\mathbf{v}|^2 + P(\rho),$$

here the pressure potential  $P(\rho)$  is related to the original pressure  $p(\rho)$  through

$$P(\rho) = \rho \int_1^\rho \frac{p(r)}{r^2} dr.$$

## **E**xamples

$$\begin{aligned} \mathsf{A}(u) &= \left(\begin{array}{c} \rho\\ \rho v \end{array}\right), \quad \mathsf{F}(u) &= \left(\begin{array}{c} \rho v\\ v \otimes v + \rho(\rho) \end{array}\right), \\ \eta(\rho, v) &= \frac{1}{2}\rho|v|^2 + P(\rho), \end{aligned}$$

We show that

$$\frac{|A(u)|}{\eta(u)} \to 0$$

as  $|u| 
ightarrow \infty$  and

$$\frac{|F(u)|}{\eta(u)} \leq C.$$

#### Shallow water magnetohydrodynamics

$$\partial_t h + \operatorname{div}_x(hv) = 0,$$
  
 $\partial_t(hv) + \operatorname{div}_x(hv \otimes v - hb \otimes b) + \nabla_x(gh^2/2) = 0,$   
 $\partial_t(hb) + \operatorname{div}_x(hb \otimes v - hv \otimes b) + v \operatorname{div}_x(hb) = 0,$ 

where g > 0 is the gravity constant,  $h: Q \to \mathbb{R}_+$  is the thickness of the fluid,  $v: Q \to \mathbb{R}^2$  is the velocity,  $b: Q \to \mathbb{R}^2$  is the magnetic field.

Consider the evolution equations of nonlinear elasticity

$$\partial_t F = \nabla_x \mathbf{v}$$
  
$$\partial_t \mathbf{v} = \operatorname{div}_x (D_F W(F)) \quad \text{in } \mathcal{X},$$

for an unknown matrix field  $F: \mathcal{X} \to \mathbb{M}^{k \times k}$ , and an unknown vector field  $\mathbf{v}: \mathcal{X} \to \mathbb{R}^k$ . Function  $W: \mathcal{U} \to \mathbb{R}$  is given. For many applications,  $\mathcal{U} = \mathbb{M}^{k \times k}_+$  where  $\mathbb{M}^{k \times k}_+$  denotes the subset of  $\mathbb{M}^{k \times k}$  containing only matrices having positive determinant.

- This general framework will not cover systems of conservation laws, which may fail to be hyperbolic, typically incompressible inviscid systems.
- We propose an extension of this framework to cover the case of incompressible fluids, in case of which the assumption that ∇A is a nonsingular matrix is not satisfied.
- We distinguish from the flux the part *L* (Lagrange multiplier) which is perpendicular to the vector G(U) (which coincides with the gradient of the entropy of the strong solution in the case A = Id).
- Thus we assume that there exists a subspace Y, such that G(U) ∈ Y and L ∈ Y<sup>⊥</sup>, where U is a strong solution to the considered system.

Let us then consider a system in the following form

 $\partial_t A(u) + \partial_\alpha F_\alpha(u) + L = 0.$ 

Examples covered by our theory:

- incompressible Euler
- incompressible magnetohydrodynamics
- inhomogeneous incompressible Euler
- incompressible inhomogeneous magnetohydrodynamics

#### Thank you for your attention